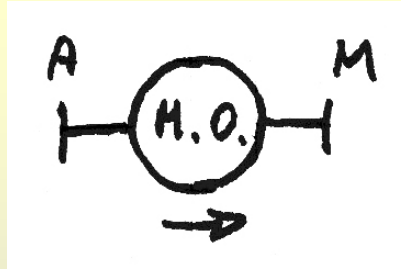


Lezione 5

Generalità sulle Macchine Operatrici

Prevalenza



- Si chiama prevalenza Y l'incremento di energia meccanica del fluido fra A ed M, al netto delle perdite

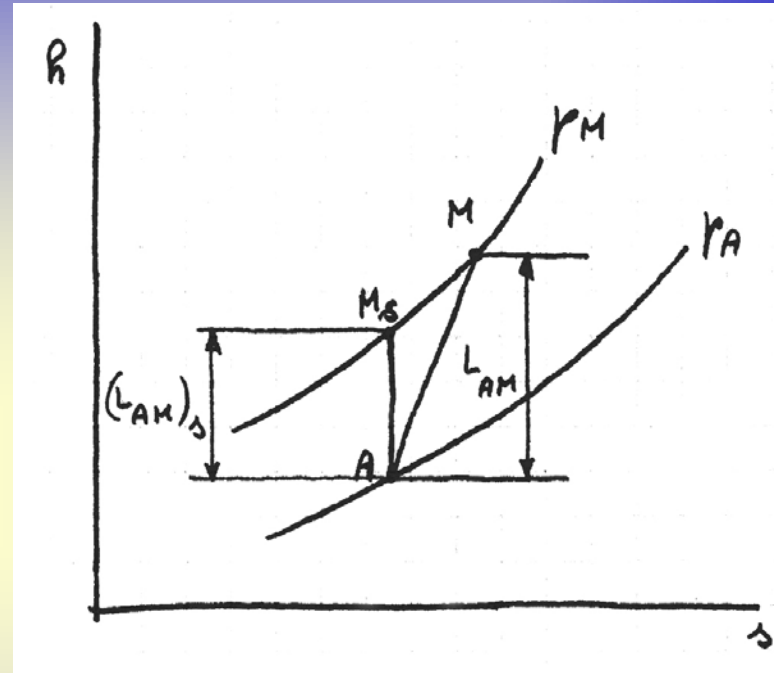
$$\frac{c_M^2 - c_A^2}{2} + g(z_M - z_A) = L'_{AM} - \int_A^M v dp - \mathcal{L}_{aAM}$$

$$Y = L'_{AM} - \mathcal{L}_{aAM}$$

Fluidi comprimibili

$$\mathcal{L}_{aAM} = (q_{eAM})_y - \left(\int_A^M T ds_e \right)_y + \int_A^M T ds_s$$

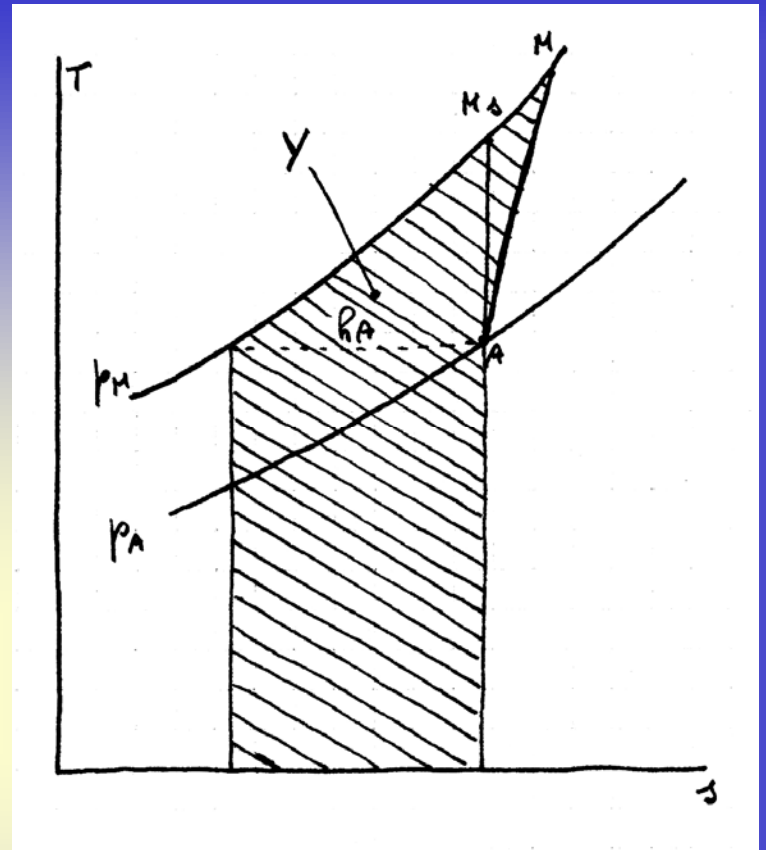
$$h_M - h_A = L'_{AM} = (L'_{AM})_y + (q_{eAM})_y$$



$$h_{M_s} - h_A = (L'_{AM})_s = L'_{AM} - \mathcal{L}_{aAM} - \left(\int_A^M v dp - \int_A^{M_s} v dp \right)$$

$$Y \approx (L'_{AM})_y$$

$$Y \approx L'_{AM} \eta_c$$



Fluidi incomprimibili

$$Y = L'_{AM} - \mathcal{L}_{aAM}$$

$$H = \frac{L'_{AM}}{g} - (\mathcal{K}_p)_{AM}$$

$$Y = gH$$

Prevalenza totale, geodetica, manometrica, cinetica

$$\frac{c_M^2 - c_A^2}{2} + g(z_M - z_A) = L'_{AM} - \int_A^M v dp - \mathcal{L}_{aAM}$$

$$Y = L'_{AM} - \mathcal{L}_{aAM}$$

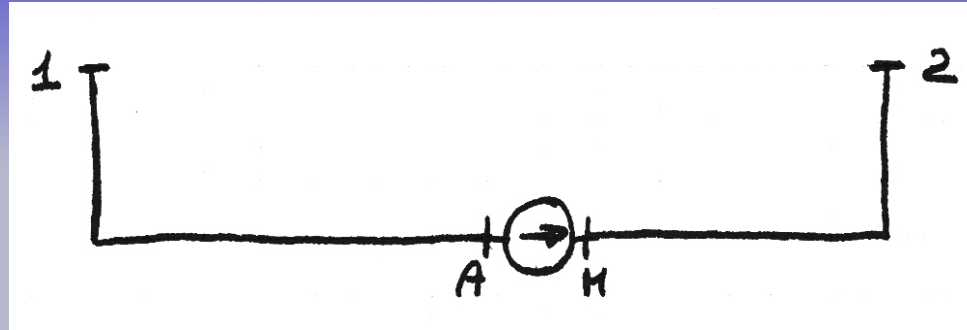
$$Y = g(z_M - z_A) + \int_A^M \frac{dp}{\rho} + \frac{c_M^2 - c_A^2}{2}$$

$$Y = Y_g + Y_m + Y_c$$

Prevalenza in forme particolari

- Pompa centrifuga Y_m
- Elica in vena libera Y_c
- Vite d'Archimede Y_g

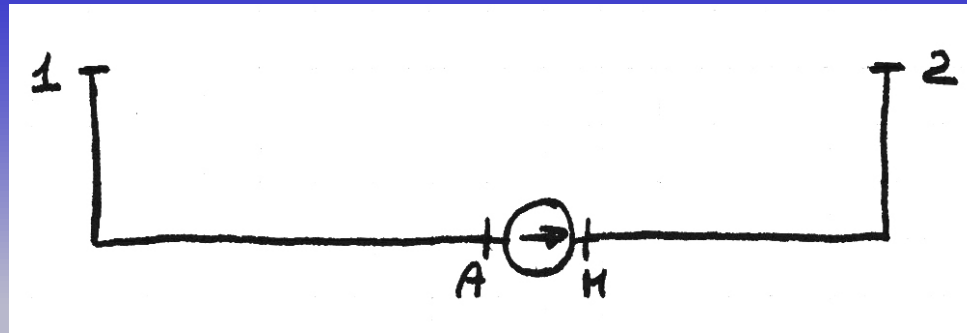
Applicazione ai circuiti



Caso elementare

$$\frac{c_1^2}{2g} + z_1 + \frac{p_1}{\rho g} = \frac{c_2^2}{2g} + z_2 + \frac{p_2}{\rho g} + \frac{\mathcal{L}_{a12}}{g} - \frac{L'_{12}}{g}$$

$$L'_{12} = L'_{AM}$$



Suddivisione delle perdite

$$\mathcal{K}_p = \mathcal{L}_a / g$$

$$\frac{c_1^2}{2g} + z_1 + \frac{p_1}{\rho g} = \frac{c_2^2}{2g} + z_2 + \frac{p_2}{\rho g} + \mathcal{K}_{p1A} + \mathcal{K}_{pM2} - \left(\frac{L'_{12}}{g} - \mathcal{K}_{pAM} \right)$$

$$\mathcal{K}_{pE} = \mathcal{K}_{p1A} + \mathcal{K}_{pM2}$$

Richiesta del circuito

$$\mathcal{K}_{pE} = \mathcal{K}_{p1A} + \mathcal{K}_{pM2}$$

$$H = (z_2 - z_1) + \frac{p_2 - p_1}{\rho g} + \frac{c_2^2 - c_1^2}{2g} + \mathcal{K}_{pE}$$

Perdite concentrate e distribuite

$$\mathcal{K}_{pE} = \sum_i \mathcal{K}'_{pi} + \sum_j \mathcal{K}''_{pj}$$

$$\mathcal{K}'_{pi} = \zeta_i \frac{c_i^2}{2g}$$

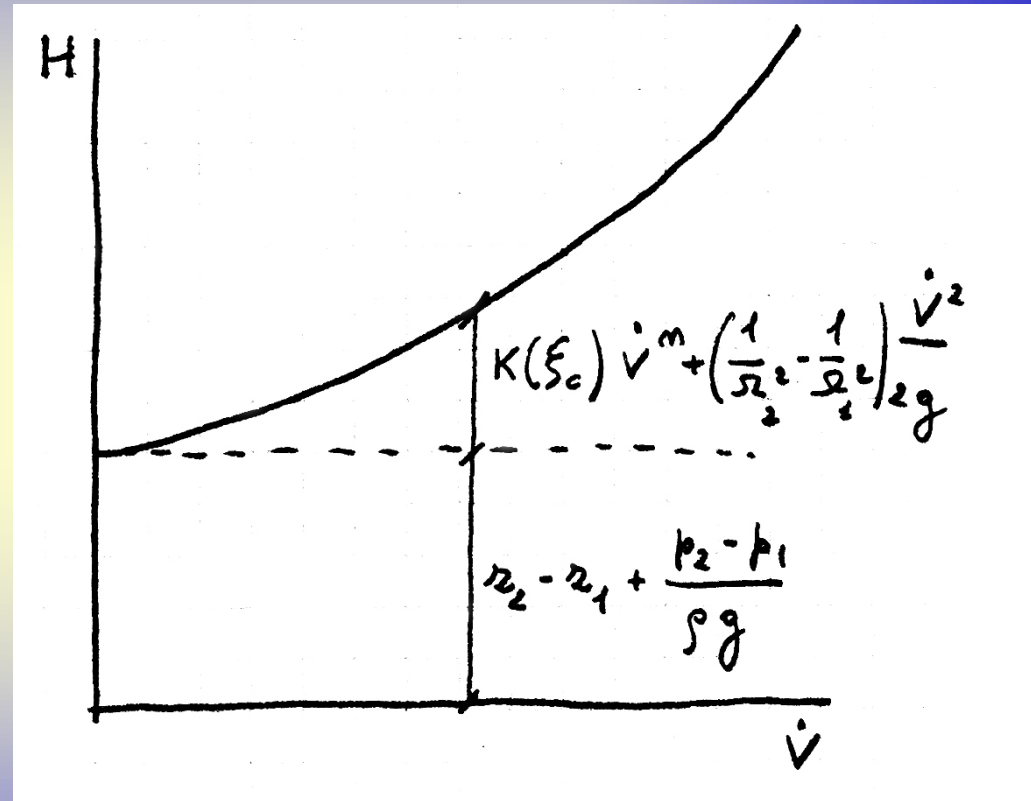
$$\mathcal{K}''_{pj} = \lambda_j \frac{\ell_j}{D_j} \frac{c_j^2}{2g}$$

Approssimazione

$$\mathcal{K}_{pE} = K(\zeta_c) \dot{V}^n$$

$$H = (z_2 - z_1) + \frac{p_2 - p_1}{\rho g} + \frac{c_2^2 - c_1^2}{2g} + \mathcal{K}_{pE}$$

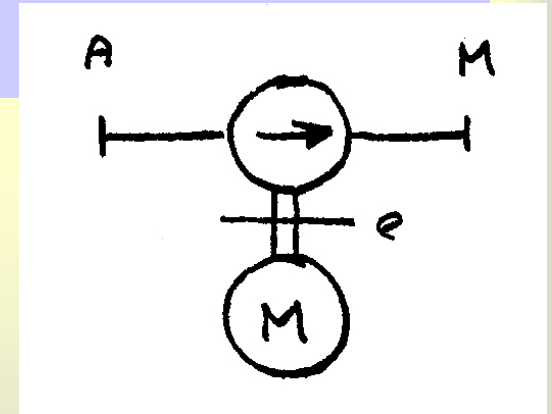
Caratteristica esterna



$$H = \left[(z_2 - z_1) + \frac{p_2 - p_1}{\rho g} \right] + \left[\left(\frac{1}{\Omega_2^2} - \frac{1}{\Omega_1^2} \right) \frac{\dot{V}^2}{2g} + K(\zeta_c) \dot{V}^n \right]$$

Funzionamento a regime della macchina operatrice

3 interfacce (fluido ; albero)



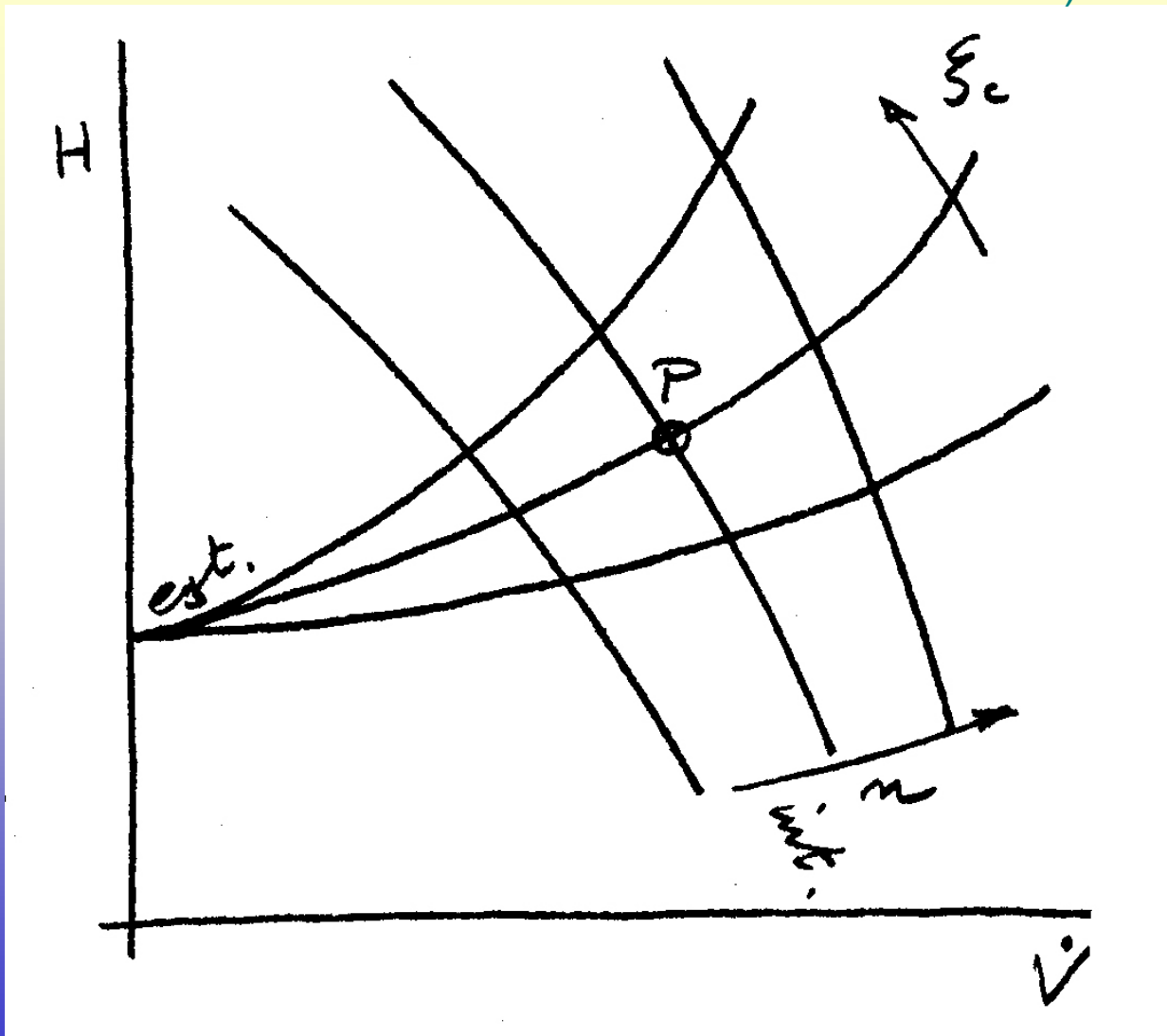
$$P_e = C_e \omega = 2\pi C_e n$$

Caratteristiche
interne

Funzionamento in equilibrio (a regime)

Prevalenza fornita = Prevalenza richiesta

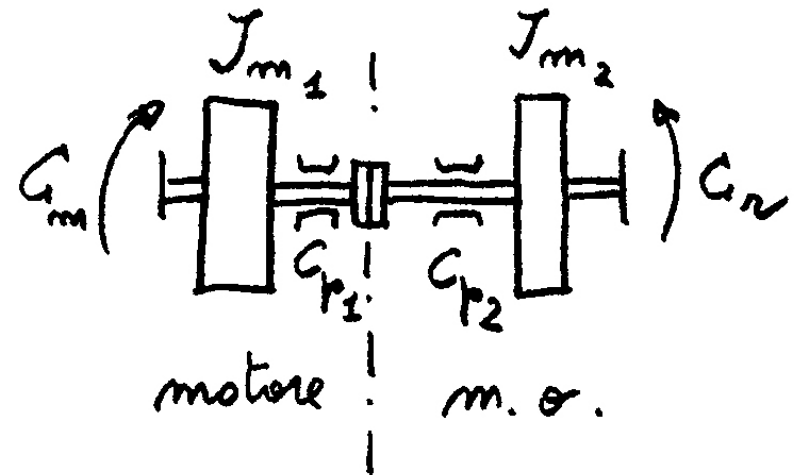
(intersezione caratteristica interna e caratteristica esterna)



Caratteristiche meccaniche

- equilibrio dinamico

$$\frac{d\omega}{dt} = \frac{C_m - C_r - \sum C_p}{\sum J_m}$$

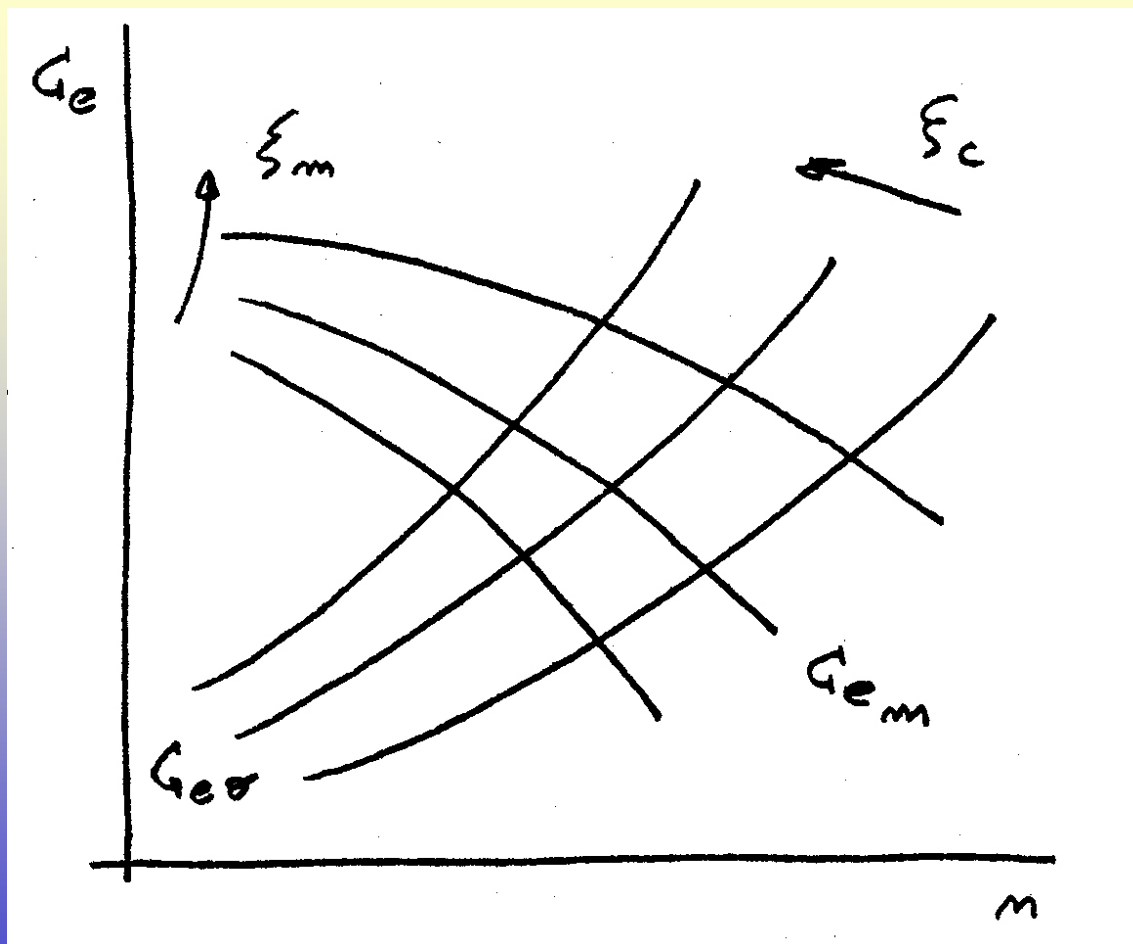


- a regime il 1° membro = 0

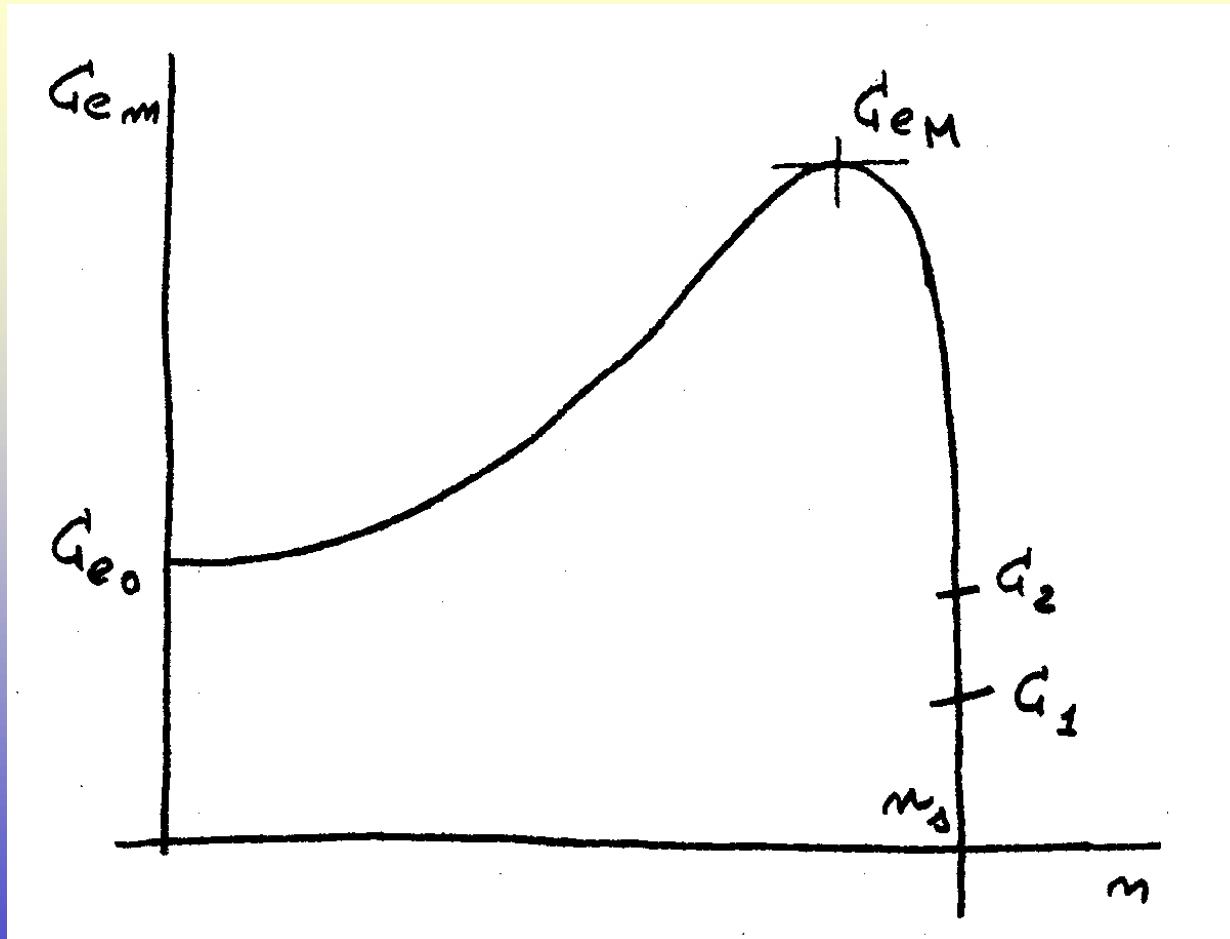
$$C_{em} = C_m - C_{p1}$$

$$C_{e0} = C_r + C_{p2}$$

Rappresentazione grafica dell'equilibrio dei momenti sull'albero

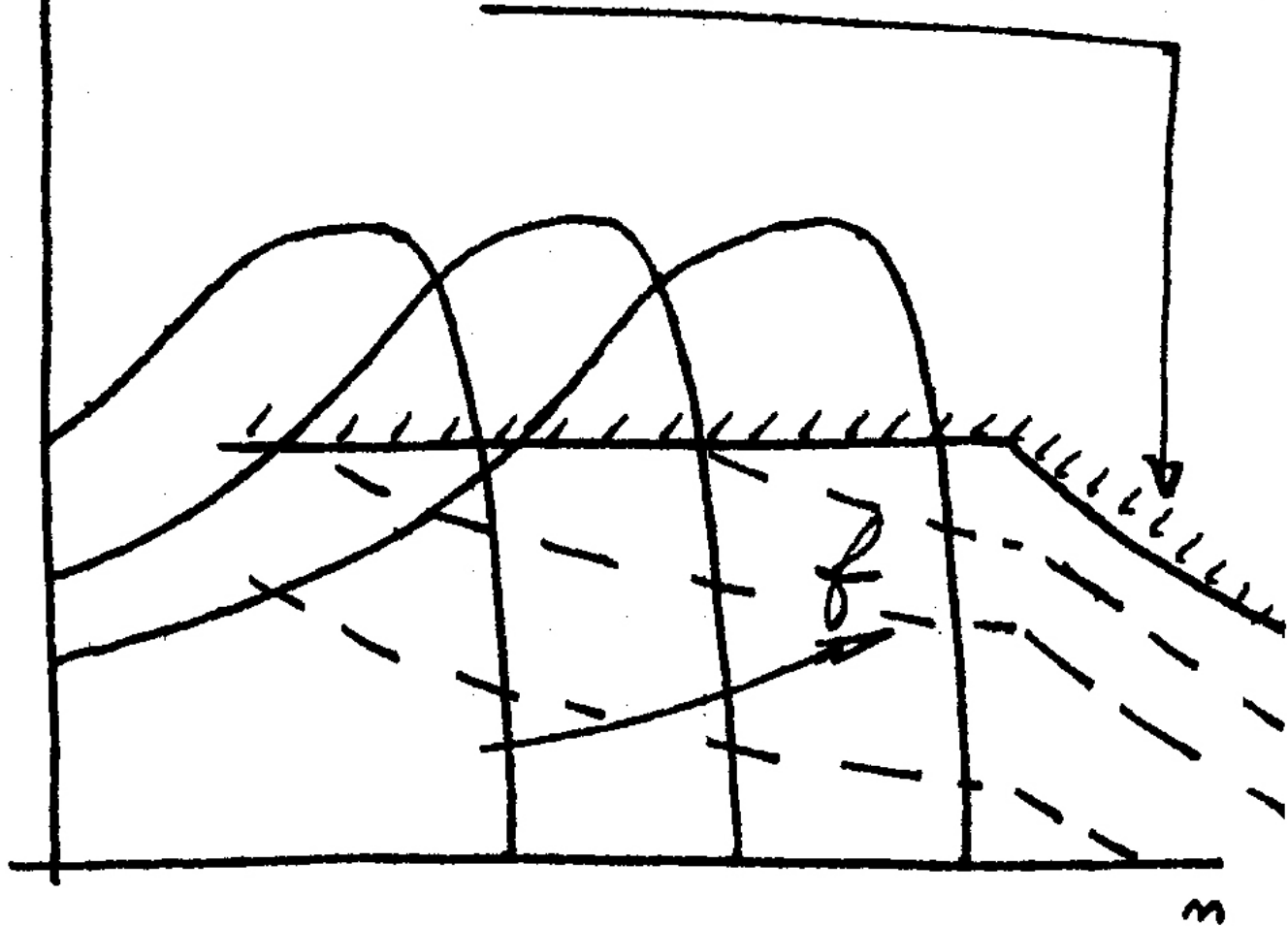


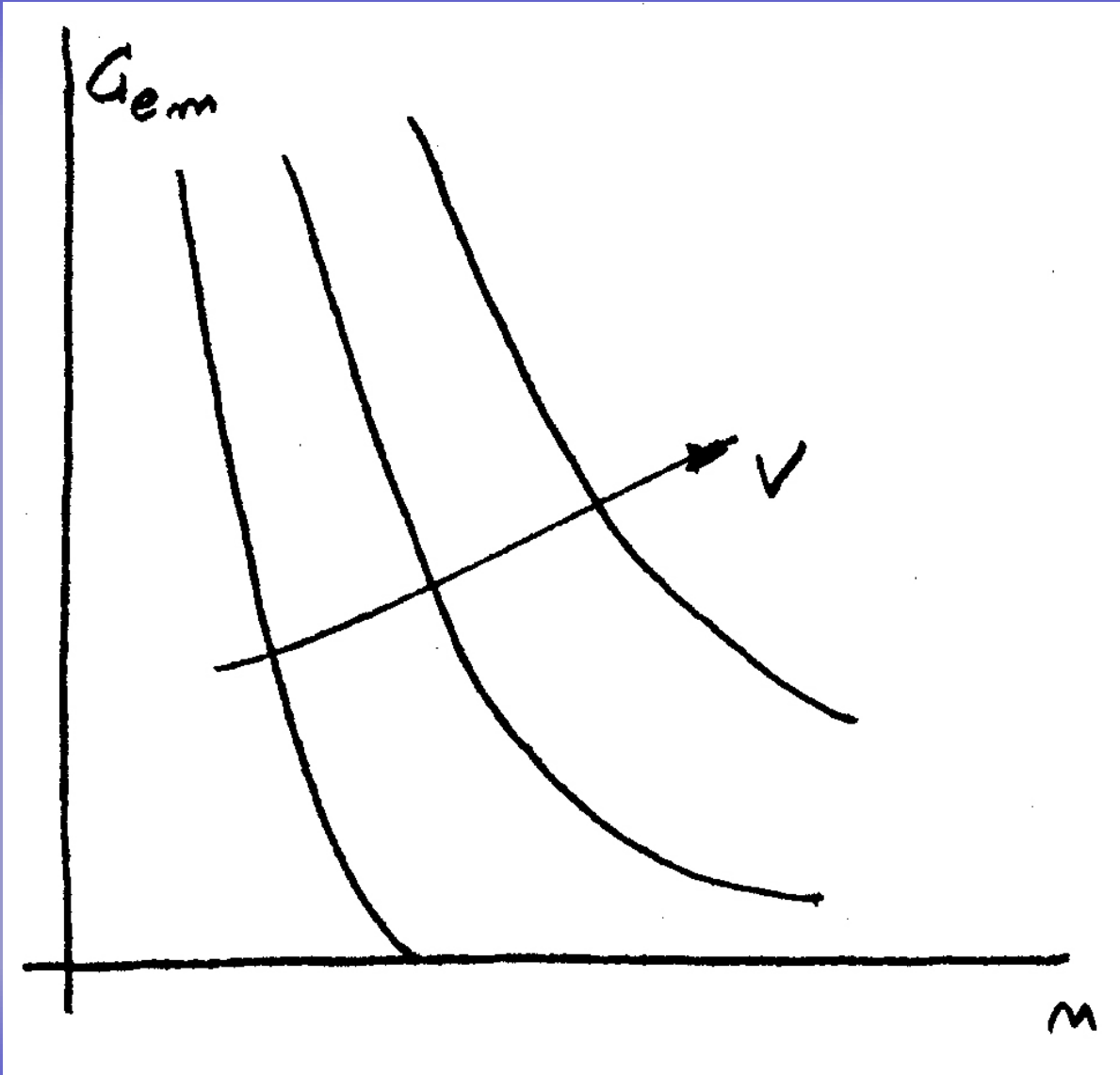
Caratteristiche meccaniche dei motori

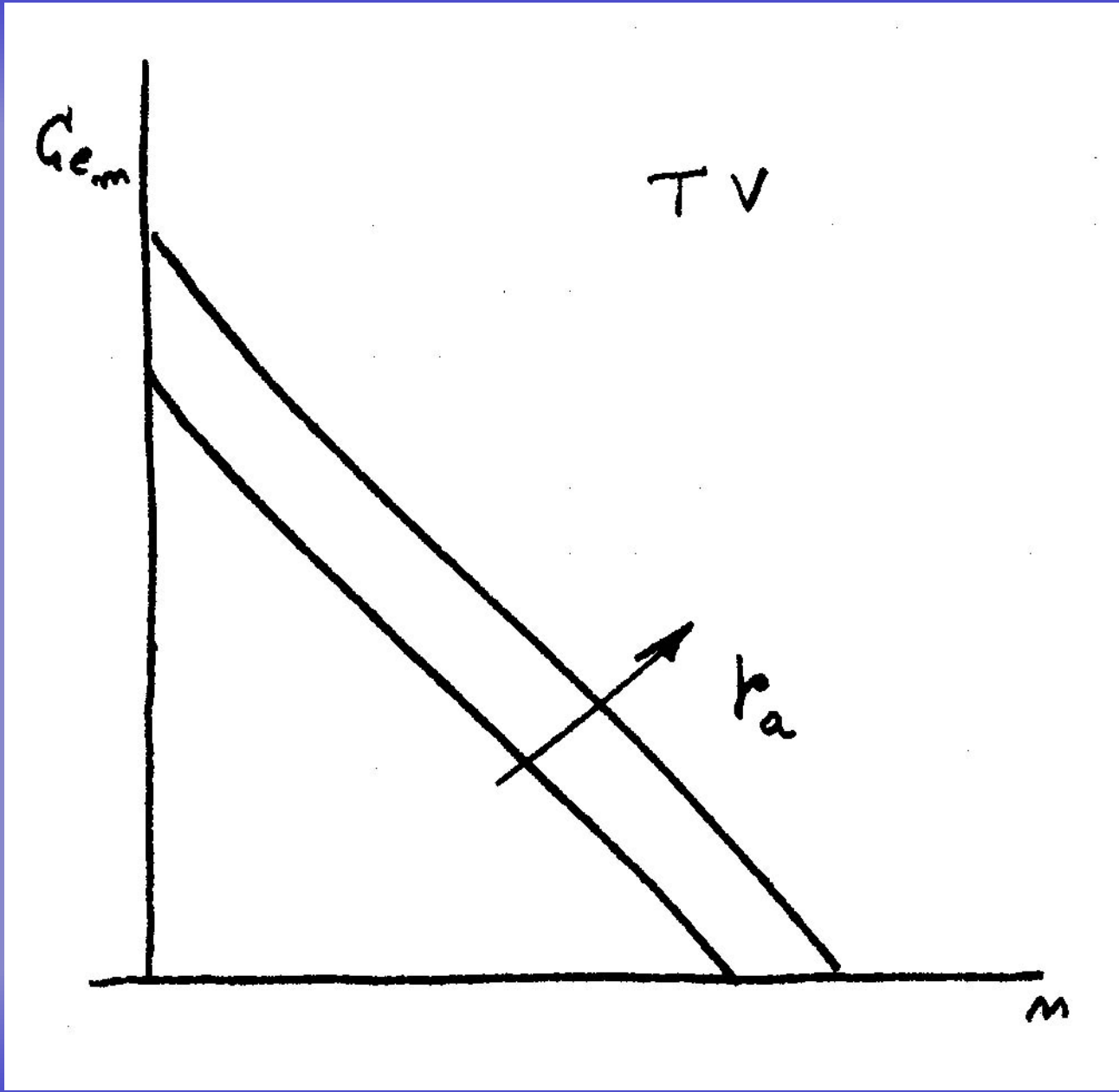


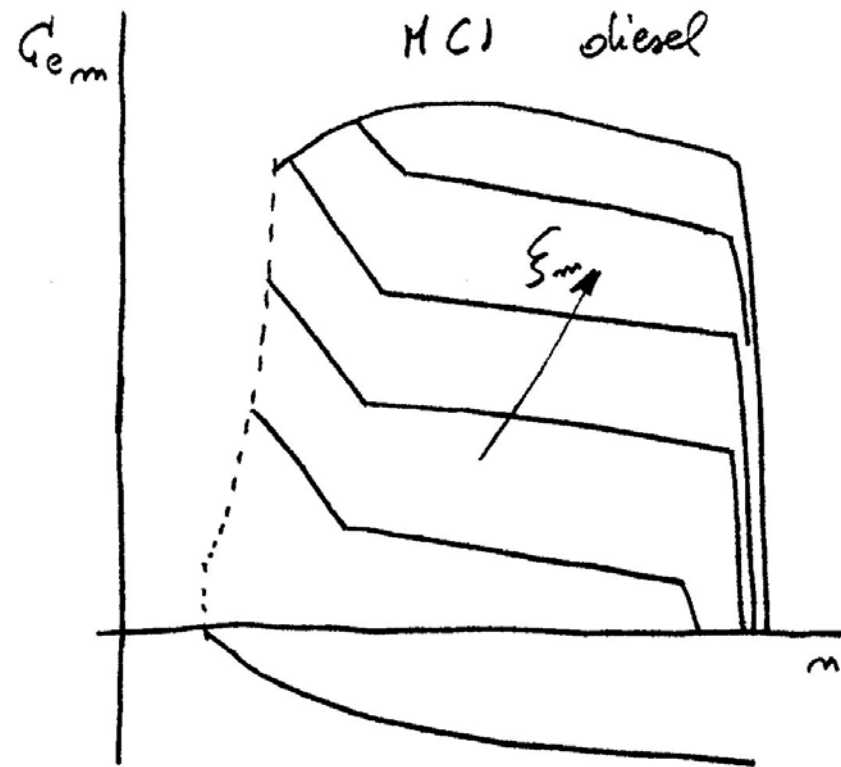
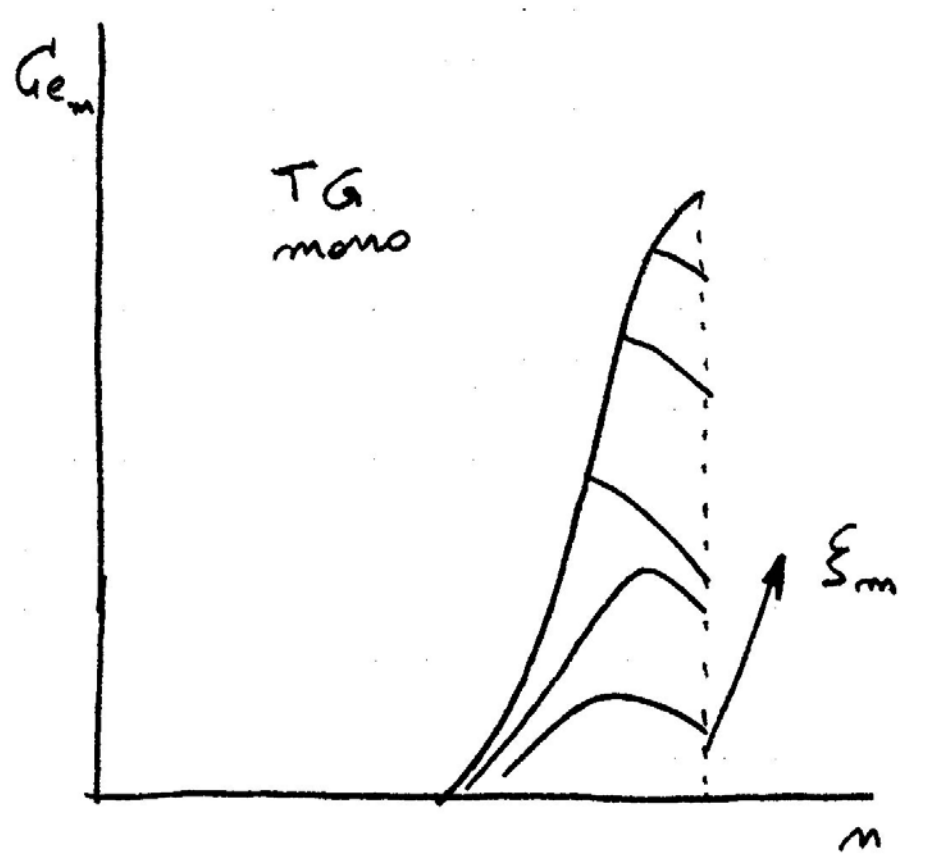
G_m

limite di fusione.









- $\frac{n_{min}}{n_{max}} \cong 0,5 \div 0,6$

TG

- $\frac{n_{min}}{n_{max}} \cong 0,12 \div 0,18$

MCI

